

Exploiting easy data in online optimization

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Joint work with

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Outline

- Online optimization
- Worst-case guarantees...
- ... and beyond
- The best of both worlds:
(AB)-Prod
- Applications
- (Proof, if there's time)

Online optimization

Parameters:

decision set S , set of loss functions $F \subseteq [0,1]^S$

For $t = 1, 2, \dots, T$ repeat

- Learner picks decision $x_t \in S$
- Environment picks loss function $f_t \in F$
- Learner suffers loss $f_t(x_t)$
- Learner observes f_t

Online optimization – examples

Prediction with expert advice:

- $S = [N] \stackrel{\text{def}}{=} \{1, 2, \dots, N\}$
- $F = [0, 1]^N$

Online convex optimization:

- S : a convex subset of R^d
- F : the set of bounded convex functions on R^d

Online combinatorial optimization:

- $S \subseteq \{0, 1\}^d$
- $F = [0, 1]^S$
- e.g., set of paths, spanning trees, matchings on a graph

+ pretty much anything
with full-information
feedback*

A central concept: Regret

$$R_T = \sum_{t=1}^T f_t(x_t) - \min_{x \in S} \sum_{t=1}^T f_t(x)$$

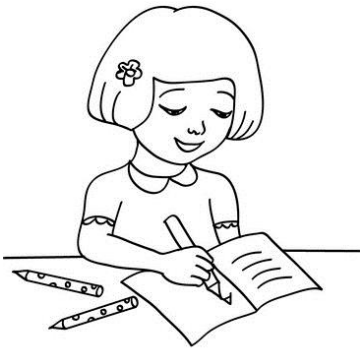
A central concept: Regret



Learner aims to choose x_1, x_2, \dots, x_T to **minimize** R_T

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Environment aims to choose f_1, f_2, \dots, f_T to **maximize** R_T



A central concept: Regret



Learner aims to choose x_1, x_2, \dots, x_T to **minimize** R_T

A typical guarantee:
 $R_T = \Theta(C\sqrt{T})$

Environment aims to choose f_1, f_2, \dots, f_T to **maximize** R_T



Beyond worst-case guarantees

- What if the **environment** is not that bad?



Beyond worst-case guarantees

- What if the **environment** is not that bad?
- Some known easy cases:



- i.i.d. losses in the experts setting:

$$R_T = O(\log N)$$

- Strongly convex losses in OCO:

$$R_T = O(\log T)$$

- i.i.d. losses in bandits:

$$R_T = O(\log T)$$

- ...

Beyond worst-case guarantees

- What if the **environment** is not that bad?
- Some known easy cases:
 - i.i.d. losses in the experts setting:
 - Strongly concave losses
 - i.i.d. losses with bounded variance
 - ...



But you need to
be aggressive to
get these!

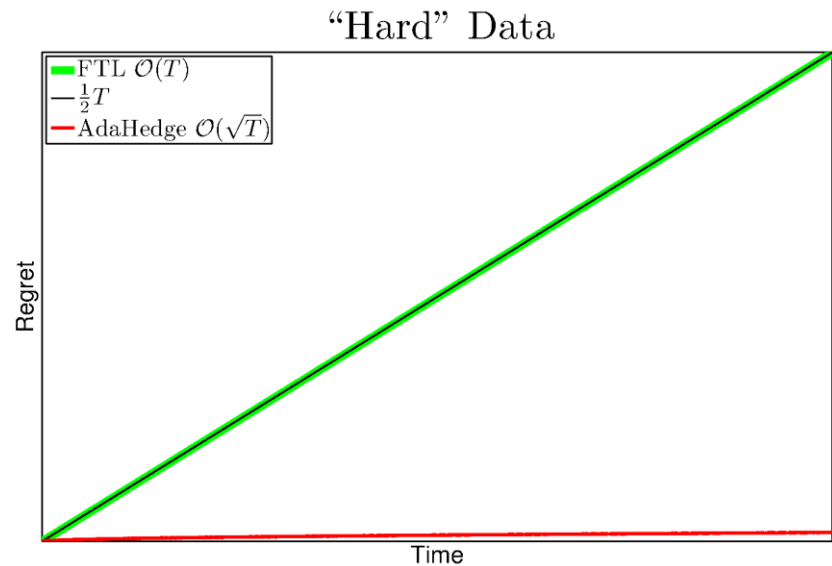
How bad can it be?

Classical counterexample:

- Two experts with losses

$$\begin{bmatrix} 1/2 & 0 & 1 & 0 & 1 & \dots \\ 0 & 1 & 0 & 1 & 0 & \dots \end{bmatrix}$$

- FTL suffers



How bad can it be?

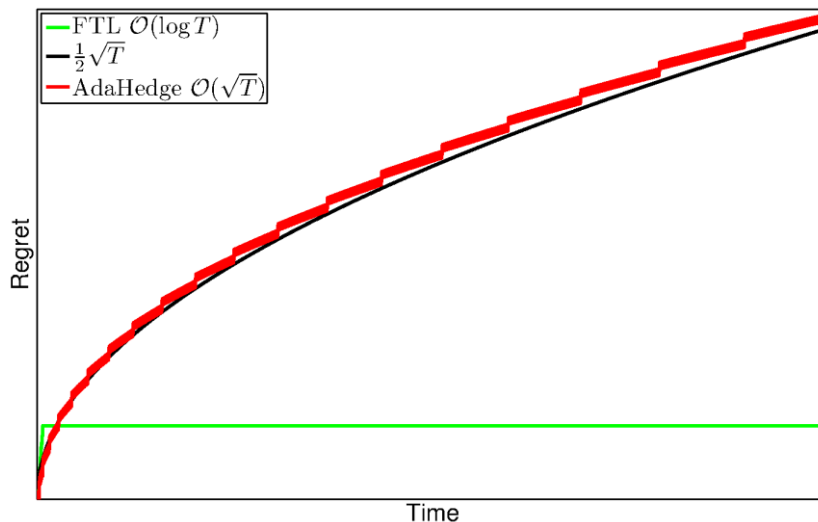
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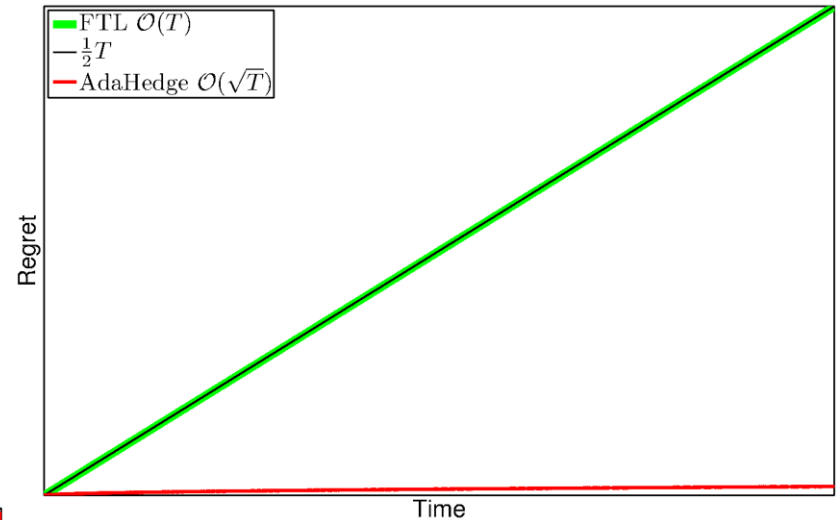
$$\begin{bmatrix} 1/2 & 0 & 1 & 0 & 1 & \dots \\ 0 & 1 & 0 & 1 & 0 & \dots \end{bmatrix}$$

- FTL suffers

“Easy” Data



“Hard” Data



Add a little twist:

- Two experts with losses

$$\begin{bmatrix} 0 & 0 & 1 & 0 & 1 & \dots \\ 1 & 1 & 0 & 1 & 0 & \dots \end{bmatrix}$$

and a few more $[0 \ 1]^T$ later

- FTL beats everything else

The best of both worlds

Some previous results:

	Easy data	Hard data
Experts (De Rooij, Van Erven, Grünwald and Koolen, 2014)	$\log N$ (for i.i.d.)	$\sqrt{T \log N}$ (standard worst-case)
OCO (Bartlett, Hazan and Rakhlin, 2007)	$\log T$ (for strongly convex)	\sqrt{T} (standard worst-case)
Bandits (Seldin and Slivkins, 2014)	$\log^3 T$ (for i.i.d.)	$\sqrt{NT \log N}$ (standard worst-case)

Is there a generic
way to combine two
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YES!!!!

Our setup

Worst-case
algorithm A

Opportunistic
benchmark B

Our setup

Worst-case
algorithm A

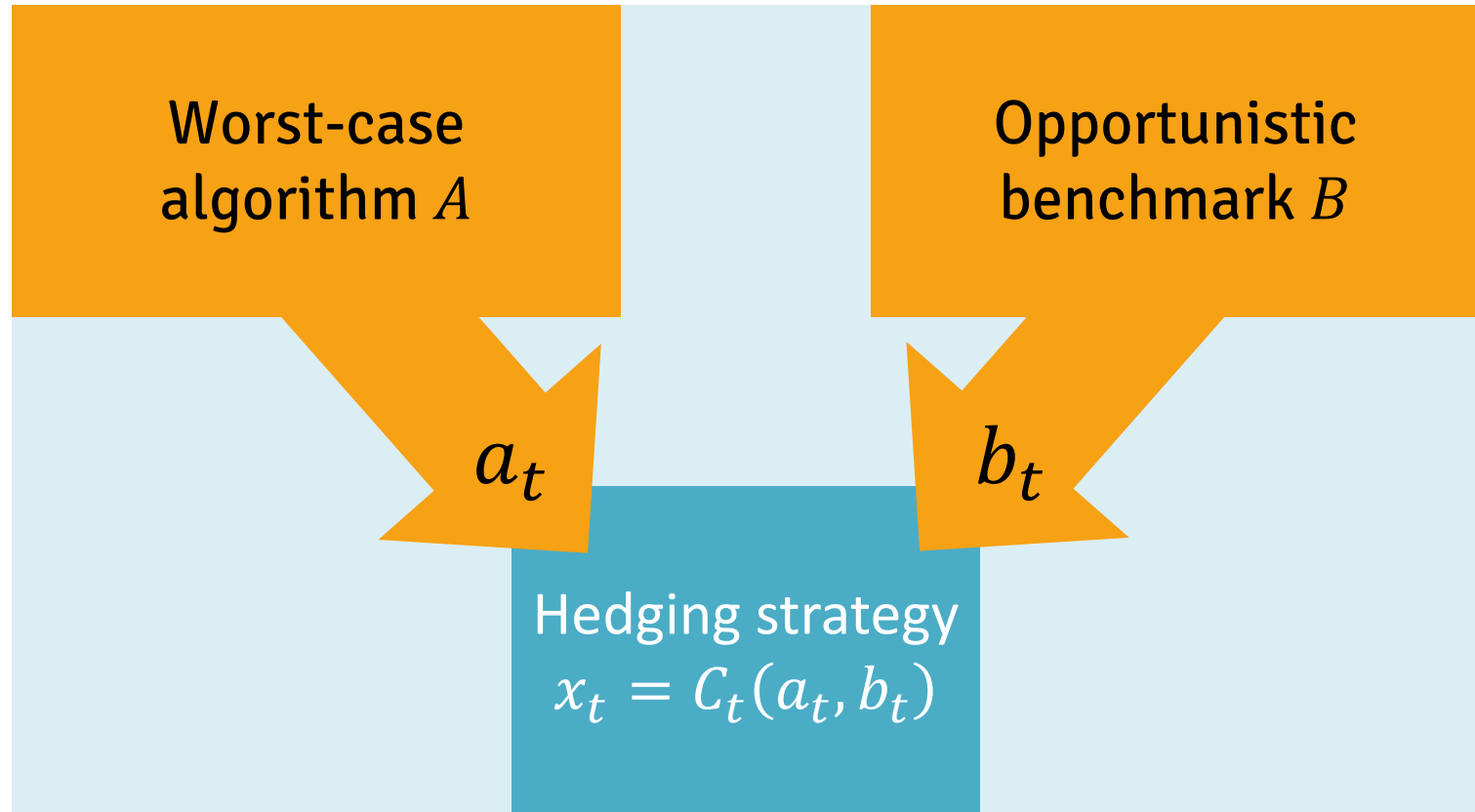
Opportunistic
benchmark B

a_t

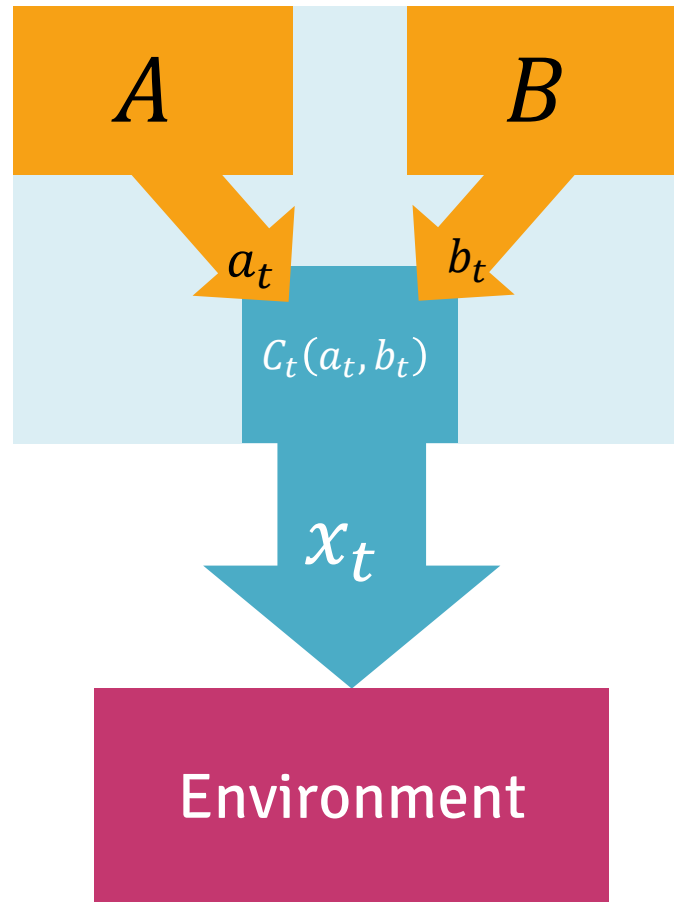
b_t

Hedging strategy
 $x_t = C_t(a_t, b_t)$

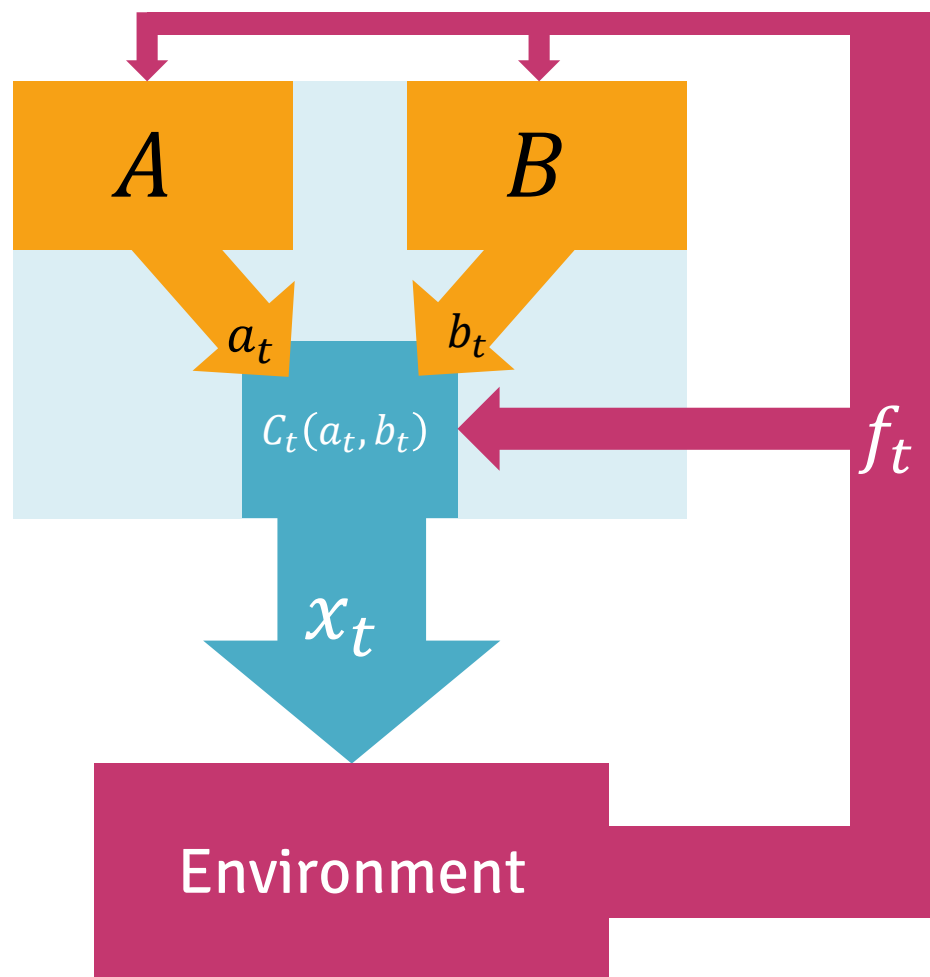
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Our setup



A naïve approach

Let's treat A and B as experts and use Hedge* on top of them!

* Vovk(1990), Littlestone and Warmuth (1994), Freund and Schapire (1997)

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Let's treat A and B as experts and use Hedge* on top of them!

Initialize $\eta > 0$, $w_{1,A} = w_{1,B} = 1/2$

For $t = 1, 2, \dots, T$ **repeat**

- $S_t = \frac{w_{t,A}}{w_{t,A} + w_{t,B}}$
- Predict $x_t = a_t$ w.p. s_t and $x_t = b_t$ otherwise
- Observe f_t and suffer loss $f_t(x_t)$
- Compute $\delta_t = f_t(a_t) - f_t(b_t)$
- Update $w_{t+1,A} = w_{t,A} e^{-\eta \delta_t}$

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A naïve approach

Let's treat A and B as experts and use Hedge* on top of them!

Initialize $\eta > 0$, $w_{1,A} = w_{1,B} = \frac{1}{2}$

For $t = 1, 2, \dots$

- $s_t = \frac{w_{t,A} f_{t,A} + w_{t,B} f_{t,B}}{w_{t,A} + w_{t,B}}$
- Predict s_t
- Observe J_t^A and J_t^B
- Compute $\delta_t = J_t^A - J_t^B$
- Update $w_{t+1,A} = w_{t,A} e^{-\eta \delta_t}$

This only guarantees
 $O(\sqrt{T})$ regret against
both A and B !!

* Vovk(1990), Littlestone and Warmuth (1994), Freund and Schapire (1997)

Our algorithm: (AB)-Prod

Let's replace Hedge by Prod*!

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* Cesa-Bianchi, Mansour and Stoltz (2007), Even-Dar, Kearns, Mansour, Wortman (2008)

Our algorithm: (AB)-Prod

Let's replace Hedge by Prod*!
... and put a large weight on B !

Initialize $\eta > 0$, $w_{1,A} = \eta$, $w_{1,B} = 1 - \eta$

For $t = 1, 2, \dots, T$ **repeat**

- $S_t = \frac{w_{t,A}}{w_{t,A} + w_{t,B}}$
- Predict $x_t = a_t$ w.p. s_t and $x_t = b_t$ otherwise
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Our main result

- Define

- $R_T(C, x) = \mathbf{E}\left[\sum_{t=1}^T (f_t(x_t) - f_t(x))\right]$

- $R_T(A, x) = \mathbf{E}\left[\sum_{t=1}^T (f_t(x_t) - f_t(a_t))\right]$

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Theorem:

$$R_T((AB)\text{-Prod}, x) \leq R_T(A, x) + 2\sqrt{T \log T}$$

$$R_T((AB)\text{-Prod}, x) \leq R_T(B, x) + 2 \log 2$$

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- The **asymmetry** of $(1 - \eta x)$ is key, e.g., $\eta = \frac{1}{2}$

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$$\begin{aligned} f_t(a_t) &= 1 \\ f_t(b_t) &= 0 \end{aligned}$$

$$\delta_t = 1$$

$$w_{t+1,A} = w_{t,A} \cdot \frac{1}{2}$$

$$\begin{aligned} f_t(a_t) &= 0 \\ f_t(b_t) &= 1 \end{aligned}$$

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Hedge:

$$w_{t+1,A} = w_{t,A} \cdot e^{-1/2}$$

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Hedge:

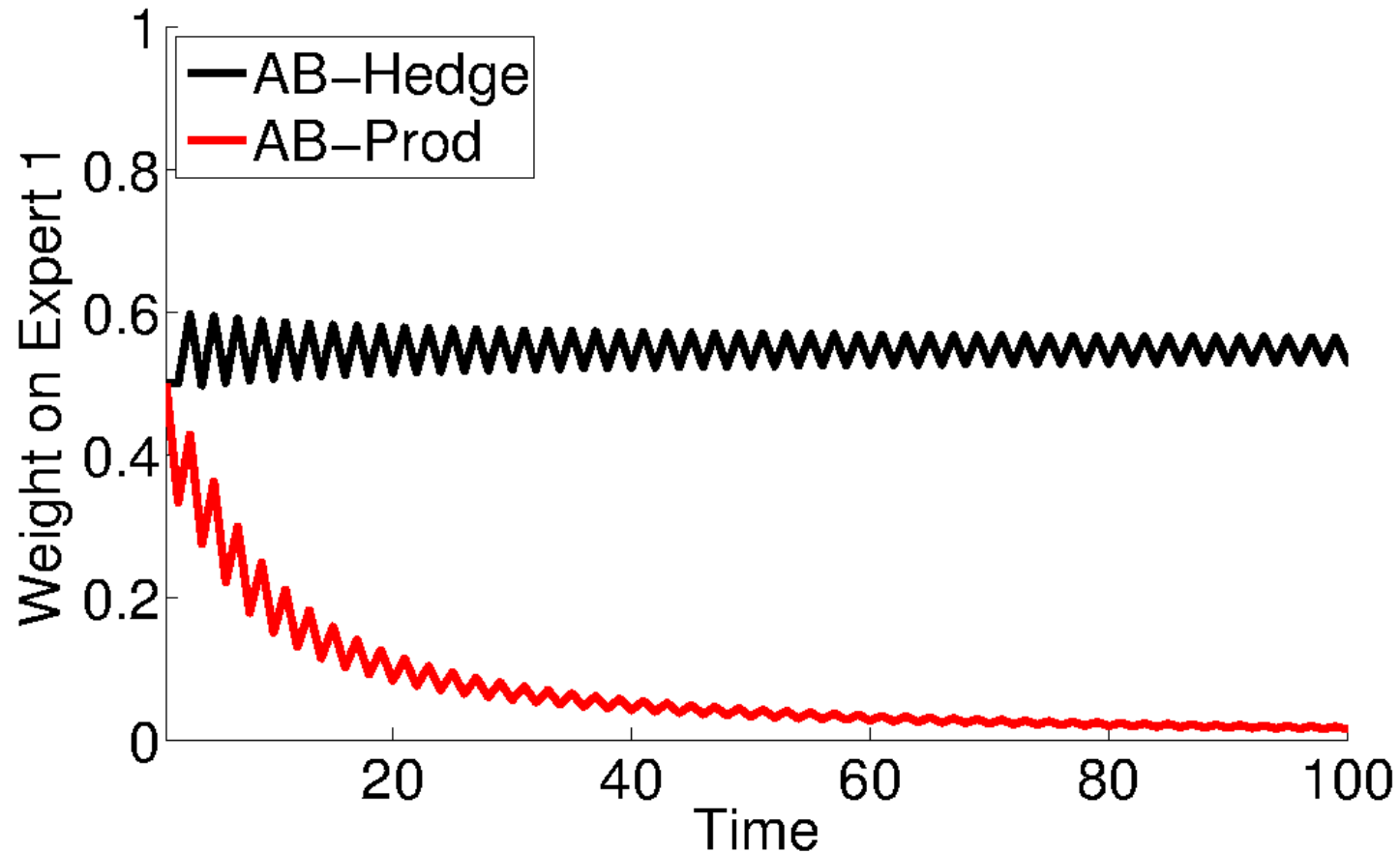
$$w_{t+1,A} = w_{t,A} \cdot e^{1/2}$$

Why does it work?

Impact of Asymmetric Update

Expert 1 Losses = {0, 1, 0, 1, 0, ..., 1}

Expert 2 Losses = {1, 0, 1, 0, 1, ..., 0}



Applications

Prediction with expert advice:

- $A = \text{Hedge}$, $B = \text{Follow the Leader}$
- **Regret:** $O(\log N)$ against i.i.d. losses,
 $O(\sqrt{T \log N} + \sqrt{T \log T})$ in worst case

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Online convex optimization:

- $A = \text{OGD}^*$ with $\eta = \frac{1}{\sqrt{t}}$, $B = \text{OGD}$ with $\eta = \frac{1}{t}$
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Applications

Tracking the best expert:

- $A = \text{Fixed Share}^*$, $B = \text{windowed FTL}$
- **Regret** measured against best sequence $x_{1:T}$ with K switches: $O(K \log(T/K))$ for piecewise i.i.d., $O(\sqrt{KT \log N} + \sqrt{T \log T})$ in worst case

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Solves COLT 2014 open problem by Koolen and Warmuth

* Herbster and Warmuth (1998)

Applications

Two-points bandit feedback:

- Observing $f_t(a_t)$ and $f_t(b_t)$ is enough!
- $A = \text{EXP3}^*$, $B = \text{UCB}^*$
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 $O(\sqrt{NT \log N} + \sqrt{T \log T})$ in worst case

Much better than the $\log^3 T$ of Seldin and Slivkins (2014), although much less general

Conclusions

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- Also guarantees that your **new** solution is essentially always better than your **old** one

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- A generic scheme to combine **aggressive** and **principled** algorithms
- Also guarantees that your **new** solution is essentially always better than your **old** one
- Open problems:
 - extending to **real** partial information?
 - reinforcement learning?
 - optimality in every single time window?

Thanks!



Proof

- Directly follows from the Prod analysis:
 - Let $S = \{1, 2, \dots, N\}$, $w_{1,i} = \mu_i$ for all i
 - In every round t , choose i w.p. $p_{t,i} \propto w_{t,i}$
 - Loss of expert i in round t : $\ell_{t,i}$
 - $w_{t+1,i} = w_{t,i} \cdot (1 - \eta \ell_{t,i})$

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Theorem (Cesa-Bianchi, Mansour and Stoltz, 2007):

If $\sum_{i=1}^N \mu_i = 1$, then for all i

$$R_{T,i} \leq \frac{\log \mu_i}{\eta} + \eta \sum_{t=1}^T \ell_{t,i}^2$$

Proof

- Idea (Even-Dar, Kearns, Mansour and Wortman, 2008):

- set $\hat{\ell}_{t,i} = \ell_{t,i} - \ell_{t,1}$

- $\mu_1 = 1 - \eta$ and $\mu_i = \frac{\eta}{N-1}$ for $i > 1$

$$R_{T,i} \leq \frac{\log \mu_i}{\eta} + \eta \sum_{t=1}^T (\ell_{t,i} - \ell_{t,1})^2$$

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$$\leq 2 \log 2$$

$$R_{T,i} \leq \frac{\log \eta}{\eta} + \eta T$$